

# Solving a System of Linear Difference Equations with Nonpredetermined Variables: Lecture Notes

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Consider the system

$$H \begin{bmatrix} y_{1,t+1} \\ \mathbf{E}_t y_{2,t+1} \end{bmatrix} = A \begin{bmatrix} y_{1t} \\ y_{2t} \end{bmatrix} + \begin{bmatrix} \varepsilon_{t+1} \\ 0 \end{bmatrix} \quad (0.1)$$

for  $t \geq 0$ , where  $y_{1t}$  is an  $n_1$ -vector of predetermined variables and  $y_{10}$  is given,  $y_{2t}$  is an  $n_2$ -vector of nonpredetermined variables,  $\varepsilon_{t+1}$  is an iid random  $n_1$ -vector with zero mean. The real matrices  $A$  and  $H$  are  $n \times n$ , where  $n \equiv n_1 + n_2$ . Take expectations conditional on information in period  $t$  and write the system as

$$H \begin{bmatrix} \mathbf{E}_t y_{1,t+1} \\ \mathbf{E}_t y_{2,t+1} \end{bmatrix} = A \begin{bmatrix} y_{1t} \\ y_{2t} \end{bmatrix} \quad (0.2)$$

Following Klein [4], Sims [5], and Söderlind [6], use the generalized Schur decomposition of  $C$ . This decomposition results in the square possibly complex matrices  $Q$ ,  $S$ ,  $T$ , and  $Z$  such that

$$A = Q'TZ', \quad (0.3)$$

$$H = Q'SZ', \quad (0.4)$$

where  $Z'$  for a complex matrix denotes the complex conjugate transpose of  $Z$  (the transpose of the complex conjugate of  $Z$ ). The matrices  $Q$  and  $Z$  are unitary ( $Q'Q = Z'Z = I$ ), and  $S$  and  $T$  are upper triangular (see Golub and van Loan [2]). Furthermore, the decomposition is sorted according to ascending modulus of the generalized eigenvalues, so  $|\lambda_j| \geq |\lambda_k|$  for  $j \geq k$ .<sup>1</sup> (The generalized eigenvalues are the ratios of the diagonal elements of  $T$  and  $S$ ,  $\lambda_j = t_{jj}/s_{jj}$  ( $j = 1, \dots, n$ ). A generalized eigenvalue is infinity if  $t_{jj} \neq 0$  and  $s_{jj} = 0$  and zero if  $t_{jj} = 0$  and  $s_{jj} \neq 0$ .)

Assume the *saddle-point property* (Blanchard and Kahn [1]): The number of generalized eigenvalues with modulus larger than unity (the unstable eigenvalues) equals the number of nonpredetermined variables. Thus, I assume that  $|\lambda_j| > 1$  for  $n_1 + 1 \leq j \leq n_1 + n_2$  and  $|\lambda_j| < 1$  for

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<sup>1</sup> The sorting of the eigenvalues is often done by two programs written by Sims and available at [www.princeton.edu/~sims](http://www.princeton.edu/~sims), Qzdiv and Qzswitch.

$1 \leq j \leq n_1$ . (for an exogenous predetermined variable with a unit root, I can actually allow  $|\lambda_j| = 1$  for some  $1 \leq j \leq n_1$ ).

Define

$$\begin{bmatrix} \tilde{y}_{1t} \\ \tilde{y}_{2t} \end{bmatrix} \equiv Z' \begin{bmatrix} y_{1t} \\ y_{2t} \end{bmatrix}. \quad (0.5)$$

I can interpret  $\tilde{y}_{1t}$  as a complex vector of  $n_1$  transformed predetermined variables and  $\tilde{y}_{2t}$  as a complex vector of  $n_2$  transformed non-predetermined variables. Premultiply the system (0.2) by  $Q$  and use (0.3)-(0.5) to write it as

$$\begin{bmatrix} S_{11} & S_{12} \\ 0 & S_{22} \end{bmatrix} \begin{bmatrix} E_t \tilde{y}_{1,t+1} \\ E_t \tilde{y}_{2,t+1} \end{bmatrix} = \begin{bmatrix} T_{11} & T_{12} \\ 0 & T_{22} \end{bmatrix} \begin{bmatrix} \tilde{y}_{1t} \\ \tilde{y}_{2t} \end{bmatrix}, \quad (0.6)$$

where  $S$  and  $T$  have been partitioned conformably with  $\tilde{y}_{1t}$  and  $\tilde{y}_{2t}$ .

Consider the lower block of (0.6),

$$S_{22} E_t \tilde{y}_{2,t+1} = T_{22} \tilde{y}_{2t}. \quad (0.7)$$

Since the diagonal terms of  $S_{22}$  and  $T_{22}$  ( $s_{jj}$  and  $t_{jj}$  for  $n_1 + 1 \leq j \leq n_1 + n_2$ ) satisfy  $|t_{jj}/s_{jj}| > 1$ , the diagonal terms of  $T_{22}$  are nonzero, the determinant of  $T_{22}$  is nonzero, and  $T_{22}$  is invertible. Note that  $S_{22}$  may not be invertible. I can then solve for  $\tilde{y}_{2t}$  as

$$\tilde{y}_{2t} = J E_t \tilde{y}_{2,t+1} = 0, \quad (0.8)$$

where the complex matrix  $J$  is given by

$$J \equiv T_{22}^{-1} S_{22}. \quad (0.9)$$

I exploit that the modulus of the diagonal terms of  $T_{22}^{-1} S_{22}$  is less than one. I also assume that  $E_t \tilde{y}_{2,t+\tau}$  are sufficiently bounded. Then  $J^\tau E_t \tilde{y}_{2,t+\tau} \rightarrow 0$  when  $\tau \rightarrow \infty$ . Note that  $J$  may not be invertible, since  $S_{22}$  may not be invertible.

I have, by (0.5),

$$y_{1t} = Z_{11} \tilde{y}_{1t}, \quad (0.10)$$

$$y_{2t} = Z_{21} \tilde{y}_{1t}, \quad (0.11)$$

where

$$Z \equiv \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \quad (0.12)$$

is partitioned conformably with  $y_{1t}$  and  $y_{2t}$ . Under the assumption of the saddle-point property,  $Z_{11}$  is square. I furthermore assume that  $Z_{11}$  is *invertible*. Then I can solve for  $\tilde{y}_{1t}$  in (0.10),

$$\tilde{y}_{1t} = Z_{11}^{-1} y_{1t}, \quad (0.13)$$

and use this in (0.11) to get

$$y_{2t} = F y_{1t}, \quad (0.14)$$

where the real  $n_2 \times n_1$  matrix  $F$  is given by

$$F \equiv Z_{21} Z_{11}^{-1}. \quad (0.15)$$

It remains to find a solution for  $y_{1,t+1}$ . By (0.8), the upper block of (0.6) is

$$S_{11} E_t \tilde{y}_{1,t+1} = T_{11} \tilde{y}_{1t}.$$

Since the diagonal terms of  $S_{11}$  and  $T_{11}$  satisfy  $|t_{jj}/s_{jj}| < 1$ , all diagonal terms of  $S_{11}$  must be nonzero, so the determinant of  $S_{11}$  is nonzero, and  $S_{11}$  is invertible. I can then solve for  $E_t \tilde{y}_{1,t+1}$  as

$$E_t \tilde{y}_{1,t+1} = S_{11}^{-1} T_{11} \tilde{y}_{1t}.$$

By (0.10),

$$\begin{aligned} E_t y_{1,t+1} &= Z_{11} E_t \tilde{y}_{1,t+1} \\ &= Z_{11} S_{11}^{-1} T_{11} \tilde{y}_{1t} \\ &= Z_{11} S_{11}^{-1} T_{11} Z_{11}^{-1} y_{1t} \end{aligned} \tag{0.16}$$

where I have used (0.13).

It follows that I can write the solution as

$$y_{1,t+1} = M y_{1t} + \varepsilon_{t+1}, \tag{0.17}$$

where the real matrix  $M$  is given by

$$M \equiv Z_{11} S_{11}^{-1} T_{11} Z_{11}^{-1} \tag{0.18}$$

Thus, the solution to the system (0.1) is given by (0.14) and (0.17) for  $t \geq 0$ .

## References

- [1] Blanchard, Olivier J., and Charles M. Kahn (1980), “The Solution of Linear Difference Models under Rational Expectations,” *Econometrica* 48, 1305–1311.
- [2] Golub, Gene H., and Charles F. van Loan (1989), *Matrix Computation*, 2nd ed., Johns Hopkins University Press, Baltimore, MD.
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